

# Vignesh Balamurugan M.B

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## EDUCATION

<b>Indian Institute of Information Technology, Sri City</b> <i>B.Tech in Artificial Intelligence &amp; Data Science</i>   CGPA: <b>8.8</b>	2023 – 2027 Sri City, India
<b>Edison G Agoram Memorial School</b> <i>CBSE XII</i>   <b>94%</b>	2021 – 2023 Chennai, India

## PROFESSIONAL EXPERIENCE

<b>Summer Intern</b> <i>National Institute of Technology (NIT), Trichy</i>	05/2025 – 07/2025 Trichy, Tamil Nadu
<ul style="list-style-type: none"><li>Researched Human Activity Detection and Recognition using <b>Vision Transformers</b>, temporal sequence modeling with <b>LSTMs</b>, and video preprocessing pipelines; delivering <b>18% accuracy improvement</b>.</li><li>Contributed to a research paper under review and engineered a <b>video captioning pipeline</b> from video input.</li><li>Minimized <b>inference latency by 22%</b> through optimized preprocessing and lightweight fine-tuning strategies.</li></ul>	

## PROJECTS

<b>RAG Fact Verification System</b>   <i>DeBERTa-v3, DPR, FAISS, RRF, MLflow</i> [GitHub]	
<ul style="list-style-type: none"><li>Constructed a multi-hop fact-verification pipeline combining Wikipedia retrieval, <b>DeBERTa-v3 NLI</b>, DPR dense retrieval, and Reciprocal Rank Fusion (RRF).</li><li>Integrated <b>3-hop evidence chaining</b> with hybrid TF-IDF + dense retrieval alongside experiment tracking via MLflow, DVC, and Prometheus/Grafana.</li></ul>	
<b>Crowd Stampede Risk Predictor</b>   <i>CANNet, ResNet-34 FPN, DroneCrowd, Temporal Risk Modeling</i> [GitHub]	
<ul style="list-style-type: none"><li>Architected a dual-head <b>CANNet (ResNet-34 FPN)</b> framework for simultaneous crowd-density estimation and person-localization from aerial surveillance footage.</li><li>Formulated a temporal crowd-risk propagation engine utilizing grid-level density evolution for proactive identification of <b>stampede-risk regions</b>.</li></ul>	
<b>Meta-Agent — Multi-Agent LLM Orchestration Framework</b>   <i>LangGraph, Redis, ChromaDB, Kubernetes HPA</i> [GitHub]	
<ul style="list-style-type: none"><li>Devised a graph-driven multi-agent orchestration framework supporting sequential, parallel, DAG-based, and hierarchical LLM execution pipelines.</li><li>Incorporated Redis/ChromaDB-backed persistent memory and an LLM-as-judge evaluation loop with Kubernetes HPA autoscaling support.</li></ul>	
<b>STRIDE — Intelligent Transportation System</b>   <i>Optical Flow, ROI Tiling, Dynamic Lattice Modeling, OpenCV</i> [GitHub]	
<ul style="list-style-type: none"><li>Proposed a <b>13-stage STRIDE architecture</b> leveraging a 2-tier parallel virtual lattice (8x8 ROI grid) for localized density, velocity, and directional traffic-flow estimation.</li><li>Engineered adaptive region-based traffic decomposition through dynamic ROI tiling and motion-vector aggregation for congestion hotspot identification.</li><li>Attained <b>0.70 IoU accuracy</b> and <b>0.69 directional-flow accuracy</b> on region-level traffic flow estimation benchmarks.</li></ul>	
<b>Chennai Night Safety Intelligence</b>   <i>QGIS, OSRM, rasterio, geopandas, Spatial MLP</i> [GitHub]	
<ul style="list-style-type: none"><li>Integrated <b>12+ geospatial datasets</b> encompassing CCTV density, police coverage, streetlight intensity, and crime heatmaps for urban risk modeling.</li><li>Orchestrated spatial-query pipelines generating <b>61 CCTV nodes, 60 streetlight clusters, and 43 patrol regions</b> using raster-vector geospatial analysis.</li><li>Trained a spatial-context MLP utilizing 9-channel neighborhood features and constructed a route-risk comparison engine yielding <b>10.5% peak risk reduction</b> with only <b>+0.25 km</b> average detour overhead.</li></ul>	
<b>RL for CRISPR Gene Editing Optimization</b>   <i>SARSA, Policy Iteration, MDPs, Drift-Aware RL</i> [GitHub]	
<ul style="list-style-type: none"><li>Modeled CRISPR gene-editing optimization as a 2D grid-world MDP and employed <b>Value Iteration, Policy Iteration, and SARSA</b> for adaptive policy learning.</li><li>Augmented the environment with non-stationary dynamics using a drift-aware hybrid RL agent for accelerated post-drift recovery.</li></ul>	

## TECHNICAL SKILLS

**AI & Machine Learning:** PyTorch, TensorFlow, Scikit-Learn, OpenCV, HuggingFace Transformers, FAISS, LangChain, LangGraph, RAG, Reinforcement Learning, Vision Transformers  
**Cloud & MLOps:** Docker, Kubernetes, GitHub Actions, MLflow, DVC, AWS, Prometheus, Grafana  
**Backend Development:** FastAPI, Flask, Node.js, REST APIs, SQLite  
**Data & GIS:** Pandas, NumPy, QGIS, geopandas, rasterio, SQL  
**Tools & Infrastructure:** Docker, Git, Linux, Postman, Vercel, Jupyter Notebook  
**Concepts:** Data Structures and Algorithms, Object-Oriented Programming, System Design, Distributed Systems, Agile  
**Languages:** Python, Java, C, SQL, JavaScript

## CERTIFICATIONS & ACHIEVEMENTS

**Supervised ML — Coursera (99.83%)** [Verify] | **Advanced Learning Algorithms — Stanford/DeepLearning.AI (100%)** [Verify]  
**Data Analytics Job Simulation — Deloitte via Forage** | **Global Game Jam 2024 — Unity game shipped**